### GRADUATE MECHANICAL ENGINEER UNIVERSITY OF COLORADO BOULDER

allisterjsequeira.github.io

🖂 allisterjames.sequeira@colorado.edu 🛛 💼 linkedin.com/in/allisterjsequeira

#### AUTOMATED VERTICAL BIKE STORAGE – CU BOULDER

Cap Sleeve for wall Pulley mount and Pulley mount Rope **Tire Clamp** Housing Button Motor

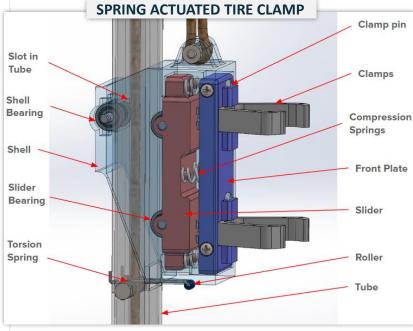
### **Overview:**

- Objective: Design a quick, reliable, and spaceoptimized, **user-centric** bike storage solution.
- Lift a 60 lb bike to its vertical position within 6 seconds and reduce overall footprint.
- Reduce lift effort by 80% using assisted lifting.
- Need finding > Ideation > Pretotype > **Prototype > Final Product**

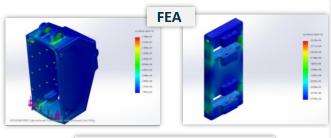
#### Execution:

- Created complete CAD model on SolidWorks including three injection molded parts having **DFA/DFM** features:
- Self-locating features
  Minimum side action
- Sufficient draft Top-Down assembly 0
- Developed functional prototypes. Rapid prototyped (3D printed) the tire clamp mechanism. Conducted user testing.
- Performed FEA for critical components.
- Prepared a technical report complete with CAD drawings, material, manufacturing and economic analysis.

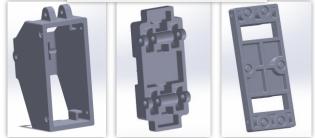




# SLEEVE REDESIGN



### **INJECTION MOLDED PARTS**



#### **Results:**

- Saved floor space by 45% and eliminated 100% lift effort through automated lifting, achieving a user-centric design.
- Improved insertion metric by 39% and reduced secondary operations by 18%.

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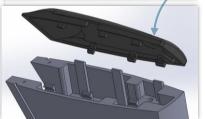
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🖂 allisterjames.sequeira@colorado.edu 🛛 肮 linkedin.com/in/allisterjsequeira

#### **REVERSE ENGINEERING A HAIR CLIPPER – CU BOULDER** Gr







### **Overview:**

- Implement design changes to reduce product cost by improving DFM/DFA metrics through reverse engineering.
- Disassembly > Initial DFA analysis > Redesign > Validation

### **Execution:**

- Redesigned parts using **DFMA principles**:
- Incorporated integral springs in the drive 0 lever, eliminated 2 compression springs.
- Added **snap fit** features to the housing, eliminated 8 screws.
- Technical report with GD&T on drawings.
- Performed fatigue analysis, material, cost and manufacturing analysis.

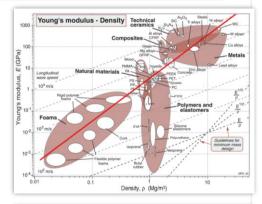
### **Results:**

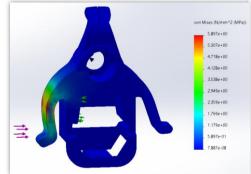
0.4 0.6 0.8

1.2 14 1.6 1.8

0.2

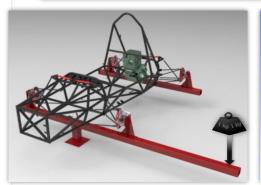
- Reduced number of components by 33%, reduced assembly time, and improved DFA metrics.
- Reduced product cost by 3.36(7.5%).





### **TORSIONAL STIFFNESS VALIDATION – FSAE SPCE RACING**

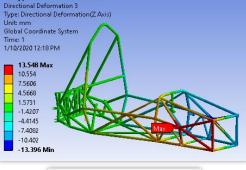
C: Copy of 3D chassis tr with rbh



### TORSIONAL RIG DESIGN

### **Overview:**

- **Objective:** Calculate torsional stiffness of **FSAE race car** using FEA and validate through testing.
- Design and fabricate a test rig to measure angular deflection due to applied torque.



### **FEA SIMULATION**

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### **STIFFNESS VALIDATION**

### **Execution:**

- Used CATIA V5 for CAD, ANSYS for FEA, and MATLAB to plot and analyze data.
- Used laser pointers to measure deflection on screen 10 ft away, increasing measurement accuracy by 9X.
- Performed inhouse fabrication, SMAW welding.

### **Results:**

Achieved acceptable 19.85% absolute error, factoring material and weld joint variations.

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in linkedin.com/in/allisterjsequeira

### FORMULA SAE RACE CAR – CHASSIS LEAD – SPCE RACING

H: 0.2 Front Impact 28-12-2018 Total Deformation Type: Total Deformation Unit: mm

Time: 1 31-12-2018 18:03

> 0.51417 0.42847 0.34278

> 0.25708

0.17139

0.085694 0 Min

0.77125 Max 0.68556 0.59986

### Design

- Designed FSAE chassis for two
  national competitions
- Used CATIA V5 for CAD
- Interdepartment coordination, interference elimination
- Accurate mounting of every component interfaced

### Analysis

- Used ANSYS for FEA
- Crash Simulation- front, side, and rear impact
- Torsional stiffness analysis and modal/vibration analysis
- Suspension and Powertrain mounts' structural analysis

### **Procurement & Fabrication**

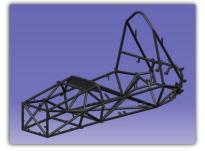
- AISI 1018 steel tubes
- Tube bending, tube laser cutting, CNC machining
- Laser cut jigsaw steel welding fixture design
- SMAW & TIG welding and Powder coating

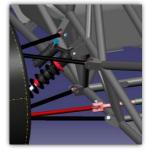
### Testing, Validation & Safety

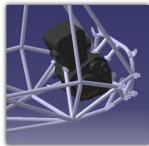
- Torsional stiffness test rig
- Driver Ergonomic design rig
- Tube tensile test
- Track testing

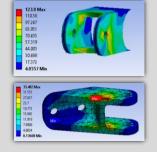
### **Reports, Presentation & Results**

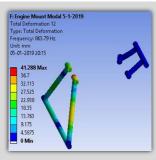
- Detailed Documentation and Technical Reports
- Presented at national competitions FB19 and FB20
- Design event: 4<sup>th</sup> rank
- Overall rank: 6<sup>th</sup> rank























PRESENTATION

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DESI

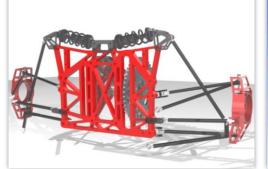
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inkedin.com/in/allisterjsequeira

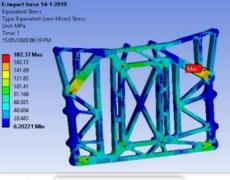
### FSAE ALUMINIUM BULKHEAD – SPCE RACING



### **CAD DESIGN RENDERING**

### **Overview:**

- Designed a detachable Al 6061 rear bulkhead for mounting the rear vehicle assemblies.
- Mountings include 75% of Suspension mounts including 4 wishbone, 2 toe, 2 rocker and 2 spring/damper mounts.
- Drivetrain mountings include 2 rear engine mounts and 2 drive spool/sprocket mounts.



### **FEA ANALYSIS**

### Execution:

- Used CATIA V5 for CAD, ANSYS for FEA analysis.
- Performed Topology Optimization achieving optimal strength and minimized weight.
- **CNC** machined for precision mounting locations.
- Anodized for improved corrosion and wear resistance, and the signature 'red' color.

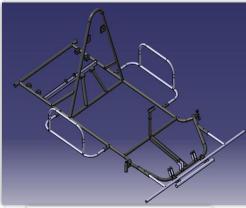


### **CNC MILLED & ANODIZED**

### **Results:**

- Improved accuracy in 80% of mountings of the complete rear assembly components.
- Eliminated misalignment of drive spool, due to uneven chain tensioning.
- Eliminated the need for complex fixtures for welding mounts by using Bolted joints.

### GO-KART – CHASSIS ENGINEER – SPCE RACING



### **CHASSIS CAD DESIGN**

### Overview:

 Designed and Fabricated a Go-kart chassis in freshman year for the national competition IKC 2018.



### **PVC PROTOTYPE**

### Execution:

- Used CATIA V5 for CAD, ANSYS for FEA analysis.
- Used **PVC pipes for prototyping** to ensure ergonomic design.
- 3D ladder frame **lowered ground clearance** to 1.5 inches, 25% lower than predecessor.



### **Results:**

 Secured 2<sup>nd</sup> Rank in the Design Event at the national competition IKC 2018.

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TANKS

'PHANTOM'

### MECHATRONICS PROJECTS – CU BOULDER 🕎





**Overview:** Map and navigate surrounding, recognize expressions & follow commands. Electronics: LiDAR, Camera, RPi, Arduino.

Contribution: Managed mechanical design

- Designed complete model, SolidWorks.
- Used 3D printed PLA for robotic claw, rack & pinion, and curling tail mechanisms. Used laser-cut acrylic sheets to build the chassis.
- Developed Arduino C++ code for claw mechanism, used servo motors.



OBJECT TRACKING CAMERA

### **Overview:**

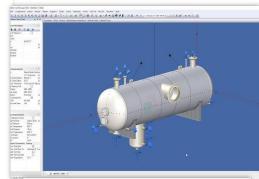
- Developed Automated object tracking camera.
- Used Pixy Camera, servo motors and Arduino.
- Application: Surveillance and Security, automated photo and videography.

**Overview:** Designed an autonomous robot tasked with launching projectiles at an opponent robot and self-reloading.

### **Contribution:**

- Developed C++ code for autonomous navigation and opponent detection.
- Used IR sensors for navigation and Pixy camera for opponent detection using Pixy camera.
- Used servo motor for turret alignment. Flywheel and **solenoid** for shooting.

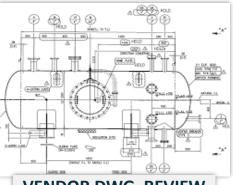
### STATIC EQUIPMENT ENGINEER – BURNS & MCDONNELL



### **COMPRESS VESSEL MODEL**

### **Responsibilities:**

- Designed Refinery Equipment like Pressure Vessels, Heat Exchangers.
- Prepared **Technical specifications** including Datasheets.
- Evaluated Vendor Bids, Reviewed Vendor Drawings, Calculations and Test Procedures.



**VENDOR DWG. REVIEW** 

### Experience:

- 2-year consultancy experience collaborating with clients and vendors.
- Managed 11 exchangers including 4" thk. vessels reaching 2000 psi and 750 °F.
- Accustomed with Industry Codes like ASME BPVC, API, PIP, client standards.



### **STACKED HEAT EXCHANGER**

### Achievements:

- Resolved equipment support design issues, eliminating major fieldwork proposed, saving the client \$10k+.
- Established adequacy of existing exchanger weld design according to Code, saving the client thousands.
- Delivered a seminar on saddle design for horizontal vessels.